

Lec 30. Homogeneous 2nd order ODE. Continued.

Ex. $y'' - y = 0$.

aux. eq. $r^2 - 1 = 0 \Rightarrow r_1 = 1, r_2 = -1$.

$$y_1(t) = e^t, \quad y_2(t) = e^{-t}$$

$$T(y) = y'' - y \equiv \left(\frac{d^2}{dt^2} - 1 \right) y$$

Fact: $\left(\frac{d}{dt} + a \right) \left(\frac{d}{dt} + b \right) = \frac{d^2}{dt^2} + (a+b) \frac{d}{dt} + ab$

$a, b \in \mathbb{C}$

$$T(y) = \left(\frac{d}{dt} - 1 \right) \left(\frac{d}{dt} + 1 \right) y = \left(\frac{d}{dt} + 1 \right) \left(\frac{d}{dt} - 1 \right) y$$

Want : $T(y) = 0$.

It is **sufficient** if

$$\left(\frac{d}{dt} + 1\right) y = 0$$



$$y' + y = 0$$

$$\text{sol: } y = e^{-t}$$

or $\left(\frac{d}{dt} - 1\right) y = 0$.



$$y' - y = 0$$

$$\text{sol: } y = e^t$$

$$\text{Ex. } \begin{cases} y'' - y = 0 \\ y(0) = 1 \\ y'(0) = 0. \end{cases} \quad \text{IVP.}$$

$$\text{General sol: } y(t) = c_1 e^t + c_2 e^{-t}$$

Need to determine c_1, c_2 . using initial data.

$$\begin{aligned} y(0) = c_1 + c_2 &= 1 \\ y'(0) = c_1 - c_2 &= 0 \end{aligned} \Rightarrow \begin{cases} c_1 = \frac{1}{2} \\ c_2 = \frac{1}{2} \end{cases}$$

$$\Rightarrow y(t) = \frac{1}{2} (e^t + e^{-t})$$

$$\underline{\text{Ex.}} \quad y'' - 2y' + y = 0$$

$$\text{aux.} \quad r^2 - 2r + 1 = (r-1)^2 = 0.$$

$$T(y) = \left(\frac{d^2}{dt^2} - 2 \frac{d}{dt} + 1 \right) y = \left(\frac{d}{dt} - 1 \right)^2 y = 0.$$

It is sufficient to have

$$\left(\frac{d}{dt} - 1 \right) y = y' - y = 0 \Rightarrow y(t) = e^t$$

Alternatively

$$\left(\frac{d}{dt} - 1 \right) y = e^t \leftarrow \text{inhomogeneous 1st order linear ODE.}$$

$$T(y) = \left(\frac{d}{dt} - 1 \right)^2 y = \left(\frac{d}{dt} - 1 \right) e^t = 0$$

$$y(t) = te^t$$

General sol $y(t) = c_1 e^t + c_2 t e^t.$

Remark: Connect to non-diagonalizable matrix.

Ex. $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$ $\lambda = 3$ (multiplicity 2)

$[A - 3I] = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ hom. eq. $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

Ask: which vectors satisfy $(A - 3I)^2 \vec{v} = \vec{0}$

Answer: $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

second sol: $(A - 3I) \vec{v}_2 = \vec{v}_1$

$$(A - 3I)^2 \vec{v}_2 = (A - 3I) \vec{v}_1 = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 0 & 1 & | & 1 \\ 0 & 0 & | & 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Case 3 : $b^2 - 4ac < 0$

Ex. $y'' - 4y' + 5y = 0$.

aux. $r^2 - 4r + 5 = 0 \Rightarrow r = \frac{4 \pm \sqrt{4^2 - 20}}{2} = 2 \pm i$

$$T(y) = \left(\frac{d}{dt} - (2+i) \right) \left(\frac{d}{dt} - (2-i) \right) y = 0.$$

$$y(t) = c_1 e^{(2+i)t} + c_2 e^{(2-i)t} \quad . \quad c_1, c_2 \in \mathbb{C}$$

$$\text{Ex. IVP. } \begin{cases} y'' - 4y' + 5y = 0 \\ y(0) = 3 \\ y'(0) = -4. \end{cases}$$

Only need to plug in initial data.

$$y(0) = C_1 + C_2 = 3$$

$$y'(0) = (2+i)C_1 + (2-i)C_2 = -4$$

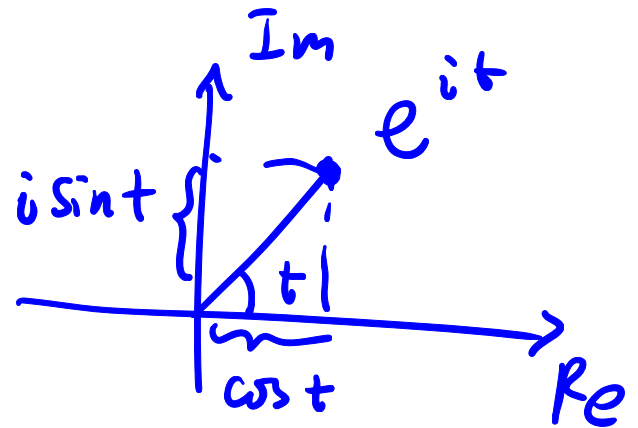
$$\Rightarrow \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} + 5i \\ \frac{3}{2} - 5i \end{bmatrix}$$

$$\Rightarrow y(t) = \underbrace{\left(\frac{3}{2} + 5i\right) e^{(2+i)t}}_{z = a+ib} + \underbrace{\left(\frac{3}{2} - 5i\right) e^{(2-i)t}}_{\bar{z} = a-ib}$$

$$= 2 \operatorname{Re} z = 2a.$$

Simplify using Euler's formula

$$e^{it} = \cos t + i \sin t$$



$$\Rightarrow y(t) = 3e^{2t} \cos 3t - 10e^{2t} \sin t \in \mathbb{R}.$$

Q: Is it possible to use real arithmetic only?

YES! Recall general sol.

$$y(t) = c_1 e^{2t} \cdot e^{it} + c_2 e^{2t} e^{-it}$$

$$= e^{2t} (c_1 \cos t + i c_1 \sin t + c_2 \cos t - i c_2 \sin t)$$

$$= e^{2t} [(c_1 + c_2) \cos t + (i c_1 - i c_2) \sin t]$$

Rename

$$= d_1 e^{2t} \cos t + d_2 e^{2t} \sin t$$

We have used.

$$\text{Span}_{\mathbb{C}} \{ e^{(2+i)t}, e^{(2-i)t} \} = \text{Span}_{\mathbb{C}} \{ e^{2t} \cos t, e^{2t} \sin t \}$$

When $y(0), y'(0) \in \mathbb{R}$

it is simpler to use $\{e^{2t} \cos t, e^{2t} \sin t\}$
as **basis**, AND let $d_1, d_2 \in \mathbb{R}$

Revisit
$$\begin{cases} y(0) = 3 \\ y'(0) = -4 \end{cases}$$

$$y(0) = d_1 = 3$$

$$y'(0) = d_1 \cdot 2 (e^{2t} \cos t) \Big|_{t=0} + d_2 e^{2t} (\cos t) \Big|_{t=0}$$

$$= 2d_1 + d_2 = -4$$

$$\Rightarrow \begin{cases} d_1 = 3 \\ d_2 = -10. \end{cases}$$

$$\Rightarrow y(t) = 3 e^{2t} \cos t - 10 e^{2t} \sin t$$

Real basis is simpler. & is

the recommended approach for computation.

Complex basis is conceptually simpler.

Inhom. 2nd order linear ODE.

The only case relevant for this class:

$$ay'' + by' + cy = t^L e^{rt}, \quad L \in \{0, 1, 2, \dots\}$$
$$r \in \mathbb{C}.$$

